

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	2480	(700/245,259,250).CQLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/09/17 09:30
L3	237	(382/153).CQLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/09/17 09:30
L4	518	(623/60,61,64).CQLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/09/17 09:30
L5	0	(294/86).CQLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/09/17 09:30
L6	1596	(414/589,591,730,744.1,749.1,754).CQLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/09/17 09:30
L7	19993	(robot mechanical machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/09/17 09:31
L8	115	7 and (12 13 14 15 16)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/09/17 09:31
L9	31	7 and (12 13 14 15 16)	US-PGPUB	OR	ON	2008/09/17 09:31

9/ 17/ 2008 9:38:46 AM

C:\Documents and Settings\wlouie1\My Documents\EAST\Workspaces\10767193-2007-07-25 object taking out apparatus.wsp